, 1	POWERED ANTITHROMBOTIC FOOT MOBILITY DEVICE
2	WITH THERAPEUTIC MASSAGE
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4	The application is a continuation-in-part of Serial Number
5	10/021,219, filed October 29, 2001, entitled "Powered
6	Antithrombotic Foot Mobility Device", which is hereby
7	incorporated by reference herein in its entirety.
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9	BACKGROUND OF THE INVENTION
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11	1. Field of the Invention
12	This invention relates broadly to exercise devices. More
13	particularly, this invention relates to exercise devices which
14	promote circulation in the lower extremities by movement of the
15	foot about a pivot and by providing a therapeutic massage.
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17	2. State of the Art
18	Deep vein thrombosis (DVT) refers to the formation of a
19	thrombus (blood clot) within a deep vein, commonly in the thigh
20	or calf. The blood clot can travel to the lungs, resulting in
21	pulmonary embolism, a potentially life-threatening condition.
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23	DVT occurs when the flow of blood is restricted in a vein,
24	and can be caused by poor circulation because of problems such
25	as heart disease, a recent heart attack or stroke, varicose
26	veins, or from inactivity or prolonged bed rest. Recently, a
27	lot of attention has been focused on DVT developed during long

airplane flights and deaths resulting therefrom. In fact, DVT 1 has been dubbed 'economy class syndrome' because the less 2 expensive seats in a plane have less leg room, limited leg 3 movement. However, DVT is not confined to economy class or to 4 5 long haul flights. 6 7 In view of current and impending lawsuits by passengers with respect to DVT, airlines have become proactive in trying to 8 9 prevent the condition and are now directing passengers to get up 10 and walk around the airplane cabin at least once an hour to 11 increase blood circulation. However, flights are subject to 12 meal service and turbulence which limit the amount of time 13 available for passengers to exercise their legs. Moreover, 14 flights are crowded and it is not feasible for all the 15 passengers to walk through the narrow aisles in the cabin. 16 17 As a response, a number of devices are being promoted to 18 increase blood circulation while a passenger remains seated. 19 For example, the LYMPHA-PRESS® SKY WALKER™ device by Mego Afek 20 of Kibbutz Afek, Israel, is a portable, foldable exercise device 21 operated from a seated position. The device includes two foot 22 pedals which are not subject to any resistance other than 23 minimal friction forces. When the user wants to increase

circulation, the pedals can be easily moved by the feet of a

user in a pedaling motion. The simple pedal movement of the

user's feet effects contraction of the calf muscles which

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1 assists in moving venous blood back to the heart, augmenting 2 arterial blood inflow and preventing thrombosis.

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However, this and similar devices have a common drawback when used for the purpose of preventing DVT on long airplane flights; they require too much effort. Even the SKY WALKER™ device, which offers substantially no resistance, requires the user to concentrate on the movement of the feet. That is, if the user concentrates on the in-flight movie or a magazine, it is easy to forget to continue to pedal and DVT can result.

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12 U.S. Patent No. 6,217,488 to Bernardson discloses another lower leg exerciser which includes a base, foot pedals which 13 14 rock along a pivot relative to the base, and a motor adapted to 15 rock the pedals back and forth. When feet are placed on the 16 pedals, the feet are rocked automatically and blood circulation 17 in the legs is increased. However, the Bernardson device has 18 several drawbacks. First, the rocking movement of the feet 19 causes the knees to move up and down. This motion is not suited 20 to airplane travel, as the room in front of a seat is limited, and once the user's feet are raised and placed on the device, 21 22 the rocking motion may cause the user's knees to contact the 23 back of the chair in front, may cause interference with a tray 24 table, or may be annoying if, e.g., trying read a book held on 25 the lap. A second drawback is that the Bernardson device cannot 26 be reconfigured to a smaller size for increased portability.

1 My previously incorporated prior application, which is parent hereto, describes a foot mobility device having a body, 2 3 two pedals rotatable about a common axis preferably in opposition to each other and relative to the body, and a motor 4 drive assembly coupled to the pedals. The feet of a user are 5 placed on the pedals, and the motor drive assembly is powered to 6 cause movement of the pedals even while the user is completely 7 passive; i.e., without any active participation by the user. 8 9 Moreover, the sensation received by the use, rather than being one of typical "exercise", is massage-like and therapeutic, all 10 11 while providing the same benefit of increased blood circulation due to contraction and relaxation of the calf muscle. Moreover, 12 13 the foot mobility device may be moved between an open 14 configuration adapted for use of the device and a collapsed 15 configuration having a low profile and adapted for storage and 16 portability. 17 18 According to one embodiment, the foot mobility device 19 includes a generally vertically oriented body, two foot pedals 20 hingedly coupled on either side of the body to rotate 21 substantially ninety degrees relative to the body between a 22 closed position in which each foot pedal is substantially 23 parallel to the body and an open position in which each foot 24 pedal is substantially perpendicular to the body. In the open 25 position, the pedals are adapted to cause feet placed thereon to 26 rotate about the ankle joint.

1 According to other embodiments, the foot mobility device includes a preferably flat base, two pedals rotatable about a 2 heel pivot, and a motor mechanism which rotates the pedals. The 3 motor mechanism is movable from a first position in which it 4 lies against the base to an upright second position in which it 5 6 is adapted to move the pedals. The pedals can be configured to lie flat against the base for storage and portability. 7 addition, the pedals can preferably be disengaged from the motor 8 drive so that the device can be used as an active exercise 9 device and also to facilitate moving the pedals for folding the 10 11 device in a highly portable configuration. 12 13 SUMMARY OF THE INVENTION 14 15 It is therefore an object of the invention to provide a 16 foot mobility device which moves the feet in a manner which 17 limits knee movement. 18 19 It is another object of the invention to provide a foot mobility device which requires no effort on the part of the 20 21 user. 22 23 It is an additional object of the invention to provide a 24 foot mobility device which is portable. 25 26 It is also an object of the invention to provide a foot 27 mobility device which has a low profile.

1 It is still another object of the invention to provide a 2 foot mobility device which has a collapsed configuration.

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It is a further object of the invention to provide a foot mobility device which includes foot massaging capability.

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It is still another object of the invention to provide a foot mobility device which operates without complex motors and gears.

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It is yet another object of the invention to provide a foot mobility device which can be used with one foot alone or in synchronization with both feet.

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15 In accord with these objects, which will be discussed in 16 detail below, a foot mobility device according to the invention 17 includes a base, a foot rest hingedly coupled to the base, and 18 an inflatable lifting bladder between the base and the foot 19 rest. The lifting bladder is coupled by a valve to a source of 20 fluid pressure. The valve is operable to inflate and deflate 21 the lifting bladder thereby raising and lowering the foot rest 22 without the use of a motor and gear assembly. The foot rest 23 preferably has a massage sock coupled to it. The massage sock 24 contains a plurality of inflatable massage bladders, each being 25 coupled by a valve to a source of fluid pressure, each of the 26 valves being operable to inflate and deflate the massage 27 bladders. Each of the bladders is preferably coupled to a

pressure sensor which determines the extent to which the bladder 1 2 has been inflated/deflated. 3 4 According to a presently preferred embodiment, the source 5 of fluid pressure is an air pump and a compressed air tank coupled to the valves and a pressure sensor. In the presently 6 7 preferred embodiment, the valves are electrically operable and 8 the pressure sensors produce electrical signals. A control circuit is electrically coupled to the valves, the sensors, and 9 the pump. The control circuit selectively inflates and deflates 10 the bladders according to a cycle which raises and lowers the 11 12 foot rest and inflates/deflates the massage bladders. 13 presently preferred control circuit is a microprocessor, ASIC (application specific integrated circuit), PLA (programmable 14 logic array) or similar circuit which will operate the valves to 15 inflate and deflate the bladders to desired pressures 16 17 (determined by the sensors) according to a programmed regime. Α 18 simple regime is to inflate bladders to 2-3 psi for 20-30 19 seconds then deflate to 0 psi in an alternating sequence 20 21 Also according to the presently preferred embodiment, the 22 control circuit is provided with a synchronization link which is used to electrically couple two foot mobility devices (one for 23 each foot) such that they operate in an alternating rhythm. 24

The presently preferred massage sock is made of elastic
material and provided with a zipper so that it may comfortably a

1 variety of foot sizes. The presently preferred number of massage bladders is seven: two under the heel, two behind the 2 3 heel, two over the instep, and one under the sole. 4 Additional objects and advantages of the invention will 5 become apparent to those skilled in the art upon reference to 6 the detailed description taken in conjunction with the provided 7 8 figures. 9 10 BRIEF DESCRIPTION OF THE DRAWINGS 11 12 Fig. 1 is a perspective view of the upper front of a foot 13 mobility device according to the invention; 14 15 Fig. 2 is a perspective view of the lower rear of the foot 16 mobility device; 17 18 Fig. 3 is a top plan view of the foot mobility device; 19 Fig. 4 is a front side elevational view of the foot 20 21 mobility device; 22 23 Fig. 5 is a perspective view of two foot mobility devices 24 and a synchronization cable; and 25 26 Fig. 6 is a schematic diagram of the electrical and 27 pneumatic components of the foot mobility device.

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2 DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENTS

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4 Turning now to Figs. 1 and 2, a foot mobility device 10 according to the invention includes a base 12, a foot rest 14 5 6 hingedly coupled to the base 12, and an inflatable lifting 7 bladder 16 between the base 12 and the foot rest 14. As described in more detail below with reference to Fig. 6, the 8 lifting bladder 16 is coupled by a valve to a source of fluid 9 pressure and the valve is operable to inflate and deflate the 10 lifting bladder thereby raising (see Fig. 1) and lowering (see 11 12 Fig. 4) the foot rest 14 without the use of a motor and gear 13 assembly. When the bladder 16 is deflated it collapses into the well 17 in the base 12 permitting the foot rest 14 to lie flus 14

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with the base.

The foot rest 14 preferably has a massage sock 18 coupled 17 18 to it. The massage sock contains a plurality of inflatable 19 massage bladders which are described in more detail below with 20 reference to Figs. 3, 4, and 6. As seen in Fig. 1, the massage sock 18 has a zipper 20 which facilitates attachment of the sock 21 22 to the user's foot. Fig. 1 also illustrates a fluid conduit 22 23 for inflating the lifting bladder 16 and a fluid conduit 24 for 24 inflating the massage bladders.

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26 Fig 2. illustrates the hinge coupling which includes the 27 interleaved members 26 and the hinge pin 28. Fig. 2 further

- 1 shows that the base 12 has removable access panels 30, 32. The
 2 panel 30 exposes a battery compartment 34 for batteries (not)
- 3 shown) to power the control circuit described below. The panel
- 4 32 exposes operational equipment such as an air pump 36, a
- 5 pressure sensor 38, and an electrically operated valve 40. An
- 6 electrical connector 42 is also shown in Fig. 2. This connector
- 7 is described in more detail below with reference to Figs. 5 and
- 8 6.

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- Referring now to Figs. 3 and 4, the illustrated embodiment
- 11 of the massage sock 18 includes seven inflatable massage
- 12 bladders: two under the heel 48, 50, two behind the heel 44, 46,
- 13 two over the instep 52, 56, and one under the sole 54. Although
- 14 Fig. 1 suggests that all of the massage bladders are inflated
- 15 from a single fluid conduit 24, separate conduits may be
- 16 provided for each bladder. As mentioned above, the base 12 of
- 17 the foot mobility device 10 includes a control circuit (not
- 18 shown in Figs. 1-5) which operates the air pump 36 and valve(s)
- 19 40 to inflate and deflate the bladders according to a programmed
- 20 regime.

- Turning now to Fig. 5, the foot mobility device 10 is
- 23 preferably used together with an identical mate. The control
- 24 circuits of each device 10 are coupled to each other via the
- 25 electrical connectors 42 and a synchronization cable 60. The
- 26 cable is provided with two n-pin electrical connectors 62, 64
- 27 which mate with connectors 42. When two foot mobility devices

are operated together, it is advantageous that one act as master 1 2 and the other as slave. This can be automatically determined by the connectors 62, 64 on the cable 60. For example, one of the 3 connectors 62, 64 can have two of its n-pins jumpered together 4 whereas the other connector does not have any pins jumpered 5 together. The foot mobility device which receives the connector 6 having the jumpered pins will sense the jumpered pins and in 7 response will act as either a master or slave, whichever is 8 predetermined by the circuit designer. When the foot mobility 9 10 devices act in master-slave relationship, one possible synchronization scheme is that the slave will wait for a signal 11 12 from the master before starting the regime. Referring now to Fig. 6, an exemplary embodiment of a

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14 15 control circuit is illustrated in conjunction with the 16 aforementioned bladders, air pump, valve and sensor. In this embodiment, the air pump 36 is coupled to a compressed air tank 17 37 which feeds a compressed air distribution conduit 39. Each 18 of the bladders is coupled by an electrically operated valve to 19 20 the conduit 39. For example, the lifting bladder 16 is coupled via conduit 22 to valve 40-0 which is coupled to the conduit 39. 21 22 The massage bladders 44-56 are similarly coupled via conduits 23 24-1 - 24-7 to valves 40-1 - 40-7 to the conduit 39. 24 the valves is also coupled to an electrical pressure sensor 38-0 25 - 38-7 which monitor the pressure in each of the bladders. 26 compressed air tank 37 is also coupled to a pressure sensor 38-27 8. All of the valves and sensors are coupled to a control

circuit 70 which is also coupled to the air pump 36, a power 1 supply 72 and a synchronization link 42 (previously referred to 2 3 an electrical connector). 4 5 The control circuit 70 operates the air pump 36 to fill the air tank 37 and selectively operates the valves to inflate and 6 deflate the bladders according to a cycle which raises and 7 lowers the foot rest and inflates/deflates the massage bladders. 8 9 The presently preferred control circuit is a microprocessor, 10 ASIC (application specific integrated circuit), PLA 11 (programmable logic array) or similar circuit which will operate 12 the valves to inflate and deflate the bladders to desired pressures (determined by the sensors) according to a programmed 13 regime. A simple regime is to inflate bladders to 2-3 psi for 14 15 20-30 seconds then deflate to 0 psi in an alternating sequence. 16 17 The circuit shown in Fig. 6 may be considered "deluxe". 18 According to simpler embodiments of the invention, fewer valves 19 and sensors may be provided and bladders may be inflated and 20 deflated in groups, rather than individually. It will also be 21 appreciated that the number of massaging bladders may be greater 22 than or fewer than the seven illustrated bladders. The power 23 supply 72 may be a battery or a group of batteries. The battery 24 may be rechargeable, and an AC adapter may be provided to avoid 25 battery consumption/depletion. The present invention

used in conjunction with my earlier device which is disclosed in

contemplates that the massage sock with massage bladders may be

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1 the parent application or in conjunction with other foot rest

2 lifting means.

- 4 There have been described and illustrated herein
- 5 embodiments of a powered foot mobility device. While particular
- 6 embodiments of the invention have been described, it is not
- 7 intended that the invention be limited thereto, as it is
- 8 intended that the invention be as broad in scope as the art will
- 9 allow and that the specification be read likewise. It will
- 10 therefore be appreciated by those skilled in the art that yet
- 11 other modifications could be made to the provided invention
- 12 without deviating from its spirit and scope.